Proportional directional valves, pilot operated, with electrical position feedback and integrated electronics (OBE)

Type 4WRKE

- Pilot operated 2-stage proportional directional valve with electrical position feedback of the main control spool and integrated electronics (OBE)
- Control of flow direction and size of a flow
- Operation by means of proportional solenoids
- Subplate mounting:
  - Porting pattern according to ISO 4401
- Electrical position feedback
- Spring-centered main control spool
- Pilot control valve:
  - Single-stage proportional directional valve
- Main stage with position control
## Ordering code

**Electrically operated**

2-stage proportional directional valve in 4-way version with integrated electronics

<table>
<thead>
<tr>
<th>Size</th>
<th>Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>16</td>
<td>16</td>
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<tr>
<td>25</td>
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<td>27</td>
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<tr>
<td>32</td>
<td>32</td>
</tr>
<tr>
<td>35</td>
<td>35</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Symbols</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Symbol 1]</td>
</tr>
<tr>
<td>![Symbol 2]</td>
</tr>
<tr>
<td>![Symbol 3]</td>
</tr>
</tbody>
</table>

With symbol E1- and \( W8- \):

- **E** = \( q_y \)
- **E1-** = \( q_y/2 \)
- **W6-** = \( q_y/2 \)
- **W8-** = \( q_y \)
- **R** = \( q_y \)
- **R3-** = \( q_y \)

With symbol **R**; **R3-**:

- **P** → **A**: \( q_y \)
- **B** → **T**: \( q_y/2 \)

- **P** → **B**: \( q_y/2 \)
- **A** → **T**: \( q_y \)

**Notice:**

In the zero position, spools W6-, W8- and R3- have a connection from A to T and B to T with approx. 2% of the relevant nominal cross-section.

### Examples

1. **Spool with spool position “a” (P → B) ordering code**: .EA or W6A
2. **Spool with spool position “b” (P → A) ordering code**: .EB or W6B
3. **Only E and W6- available with characteristic curve form L (linear)***
4. **When replacing the component series 2X with component series 3X the electronics interface is to be defined with A5 (enable signal at pin C)**

### Further details in the plain text

- **M** = NBR seals
- **V** = FKM seals
- **D3** = With pressure reducing valve
  - ZDR 6 DP0-4X/40YM-W80
    - (non-adjustable)

### Electronics interface

- **C1** = Command value/actual value ±10 mA
- **A1** = Command value/actual value ±10 V
- **F1** = Command value/actual value 4 to 20 mA

### Electrical connection

- **K31** = Without mating connector with connector according to DIN EN 175201-804
  - Mating connector – separate order
  - see page 21

### Pilot oil supply and drain

- **no code** = Pilot oil supply external, pilot oil drain external
- **E** = Pilot oil supply internal, pilot oil drain external
- **ET** = Pilot oil supply internal, pilot oil drain internal
- **T** = Pilot oil supply external, pilot oil drain internal

### Supply voltage

- **Direct voltage 24 V**
- **6E** = Proportional solenoid with detachable coil
  - Component series 30 to 39
  - (30 to 39: Unchanged installation and connection dimensions)

### Characteristic curve form

- **3X** = Linear
- **G24** = Linear with fine control range

### Rated flow

<table>
<thead>
<tr>
<th>Flow</th>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>25</td>
<td>10</td>
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<tr>
<td>50</td>
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<td>100</td>
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<td>125</td>
<td>16</td>
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<td>150</td>
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<td>200</td>
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<td>220</td>
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<td>4000</td>
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</tr>
<tr>
<td>5000</td>
<td>35</td>
</tr>
<tr>
<td>1000</td>
<td>35</td>
</tr>
</tbody>
</table>

---

1) **Examples:** Spool with spool position “a” (P → B) ordering code .EA or W6A
2) **Spool with spool position “b” (P → A) ordering code .EB or W6B
3) Only E1- and W8- available with characteristic curve form L (linear)
4) When replacing the component series 2X with component series 3X the electronics interface is to be defined with A5 (enable signal at pin C)
Symbols

Simplified

Example:
Pilot oil supply external
Pilot oil drain external

Detailed

Example:
1 Pilot control valve type 4WRAP 6...
2 Main valve
3 Pressure reducing valve
type ZDR 6 DP0-4X/40YM-W80
4 Integrated electronics (OBE)
**Function, section**

**Pilot control valve type 4WRAP 6 W7.3X/G24... (1st stage)**

The pilot control valve is a direct operated proportional valve. The control edge dimensions have been optimized for use as a pilot control valve for proportional directional valves type 4WRKE.

The proportional solenoids are pressure-tight, wet-pin AC solenoids with detachable coils. They transfer electric current proportionally into mechanical force. An increase of the current strength results in a correspondingly higher magnetic force. The set magnetic force remains the same during the total control stroke.

The pilot control valve mainly consists of the housing (1), the proportional solenoid (2 and 3), the valve control spool (4) and springs (5 and 6).

In a non-actuated state both actuators are connected to the tank. If one of the two solenoids (2 or 3) is excited, the magnetic force will move the valve control spool (4) towards the spring (5 or 6).

After having overcome the overlap area, the connection of one of the two actuators is blocked and the connection to the pressroom is made. There is a flow from P to the control chamber of the main stage.
Function, section, valve particularities

Valves of type 4WRKE are 2-stage proportional directional valves. They control the flow direction and size.

The main stage is position-controlled so that the control spool position is independent from flow forces also in the case of bigger flows.

The valves mainly consist of the pilot control valve (1), the housing (8), the main control spool (7), the covers (5 and 6), the centering spring (4), the inductive position transducer (9) and the pressure reducing valve (3).

If there is no input signal, the main control spool (7) will be kept in the central position by the centering spring (4). Both control chambers in the covers (5 and 6) are connected to the tank via the valve control spool (2).

The main control spool (7) is connected to suitable control electronics via the inductive position transducer (9). Both the change of position of the main control spool (7) and the change of the command value at the junction summing of the amplifier create a differential voltage.

During the comparison of command and actual value a possible control deviation is determined via the electronics and the proportional solenoid of the pilot control valve (1) is supplied with current.

The current induces a force in the solenoid which operates the control spool via a plunger in a row. The flow which has been released via the control cross sections causes an adjustment of the main control spool.

The main control spool (7) with the core of the inductive position transducer (9) attached to it displaced until the actual value corresponds to the command value. In a controlled state the main control spool (7) is balanced and kept in this control position.

The control spool stroke and the control opening change proportionally to the command value.

The control electronics are integrated in the valve. By adjusting valve and electronics, the deviation in series production of the devices is kept low.

The tank lines must not be allowed to run empty; a preload valve is to be installed in the case of a corresponding installation condition (counterbalance pressure approx. 2 bar).

Valve particularities

- The 2nd stage is mainly built up from components of our proportional valves.
- The zero point adjustment at “zero point main stage” is made at the factory and can be adjusted in a range of ±30% of the nominal stroke via a potentiometer in the control electronics. Access in the integrated control electronics by removing a plug screw on the front side of the cover housing.
- When the pilot control valve or the control electronics are exchanged, they are to be re-adjusted. All adjustments may be implemented by instructed experts only.

Notice!

Changes in the zero point may result in damage to the system and may only be implemented by instructed specialists!
# Technical data

## general

<table>
<thead>
<tr>
<th>Sizes</th>
<th>Size</th>
<th>10</th>
<th>16</th>
<th>25</th>
<th>27</th>
<th>32</th>
<th>35</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installation position and commissioning information</td>
<td>Preferably horizontal, see RE 07800</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Storage temperature range °C</td>
<td>–20 to +80</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ambient temperature range °C</td>
<td>–20 to +50</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Weight kg</td>
<td>8.7</td>
<td>11.2</td>
<td>16.8</td>
<td>17</td>
<td>31.5</td>
<td>34</td>
<td></td>
</tr>
<tr>
<td>Sine test according to DIN EN 60068-2-6:2008 1)</td>
<td>10 cycles, 10...2,000 Hz with logarithmic frequency changing speed of 1 oct./min, 5 to 57 Hz, amplitude 1.5 mm (p-p), 57 to 2,000 Hz, amplitude 10 g, 3 axes</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Random test according to DIN EN 60068-2-64:2009 1)</td>
<td>20...2,000 Hz, amplitude 0.05 g²/Hz (10 gRMS) 3 axes, testing time 30 min per axis</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Shock test according to DIN EN 60068-2-27:2010 1)</td>
<td>Half sine 15 g / 11 ms, 3 times in positive and 3 times in negative direction per axis, 3 axes</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Humid heat, cyclic according to DIN EN 60068-2-30:2006</td>
<td>Variant 2 +25 °C to +55 °C, 90% to 97% relative humidity, 2 cycles with 24 hours each</td>
<td></td>
<td></td>
<td></td>
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<td></td>
</tr>
</tbody>
</table>

1) The information on mechanical load applies to the fastening level of the integrated valve electronics.

## hydraulic (measured at \( p = 100 \) bar with HLP46 at 40 °C ± 5 °C)

<table>
<thead>
<tr>
<th>Operating pressure</th>
<th>Pilot control valve</th>
<th>Pilot oil supply</th>
<th>bar</th>
<th>25 to 315</th>
</tr>
</thead>
<tbody>
<tr>
<td>Main valve, connection P, A, B</td>
<td>bar</td>
<td>Up to 315</td>
<td>Up to 350</td>
<td>Up to 350</td>
</tr>
<tr>
<td>Return flow pressure</td>
<td>Connection T</td>
<td>Pilot oil drain, internal</td>
<td>bar</td>
<td>Static &lt; 10 (pilot control valve)</td>
</tr>
<tr>
<td></td>
<td>Pilot oil drain, external</td>
<td>bar</td>
<td>Up to 315</td>
<td>Up to 250</td>
</tr>
<tr>
<td>Connection Y</td>
<td>bar</td>
<td>Static &lt; 10 (pilot control valve)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rated flow ( q_{\text{nom}} \pm 10% ) with ( \Delta p = 10 ) bar</td>
<td>l/min</td>
<td>–</td>
<td>125</td>
<td>–</td>
</tr>
<tr>
<td>( \Delta p ) = valve pressure differential</td>
<td>25</td>
<td>150</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td>50</td>
<td>200</td>
<td>220</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td>100</td>
<td>220</td>
<td>350</td>
<td>500</td>
</tr>
<tr>
<td>Recommended maximum flow</td>
<td>l/min</td>
<td>170</td>
<td>460</td>
<td>870</td>
</tr>
<tr>
<td>Pilot oil flow at port X and/or Y with stepped input signal from 0 to 100% (315 bar)</td>
<td>l/min</td>
<td>4.1</td>
<td>8.5</td>
<td>11.7</td>
</tr>
<tr>
<td>Hydraulic fluid</td>
<td>See table page 7</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Maximum admissible degree of contamination of the hydraulic fluid - cleanliness class according to ISO 4406 (c)</td>
<td>Pilot control valve: Class 17/15/12 1)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Main stage: Class 20/18/15 1)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hydraulic fluid temperature range °C</td>
<td>–20 to +80, preferably +40 to +50</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Viscosity range mm²/s</td>
<td>20 to 380, preferably 30 to 45</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hysteresis %</td>
<td>( \leq 1 )</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Response sensitivity %</td>
<td>( \leq 0.5 )</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1) The cleanliness classes stated for the components need to be maintained in hydraulic systems. Effective filtration prevents faults and simultaneously increases the life cycle of the components.

For the selection of the filters see www.boschrexroth.com/filter
Technical data (for applications outside these parameters, please consult us!)

<table>
<thead>
<tr>
<th>Hydraulic fluid</th>
<th>Classification</th>
<th>Suitable sealing materials</th>
<th>Standards</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mineral oils and related hydrocarbons</td>
<td>HL, HLP</td>
<td>NBR, FKM</td>
<td>DIN 51524</td>
</tr>
<tr>
<td>Flame-resistant – containing water</td>
<td>HFC (Fuchs HYDROTHERM 46M, Petrofer Ultra Safe 620)</td>
<td>NBR</td>
<td>ISO 12922</td>
</tr>
<tr>
<td>Phosphoric acid ester</td>
<td>HFD-R</td>
<td>FKM</td>
<td></td>
</tr>
</tbody>
</table>

**Important information on hydraulic fluids!**
- For more information and data on the use of other hydraulic fluids refer to data sheet 90220 or contact us!
- There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.)!
- The flash point of the process and operating medium used must be 40 K greater than the maximum solenoid surface temperature.

**electrical**

<table>
<thead>
<tr>
<th>Voltage type</th>
<th>Direct voltage</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signal type</td>
<td>Analog</td>
</tr>
<tr>
<td>Maximum power</td>
<td>W 72 (average = 24 W)</td>
</tr>
<tr>
<td>Electrical connection</td>
<td>Mating connector according to DIN EN 175201-804</td>
</tr>
<tr>
<td>Protection class of the valve according to EN 60529</td>
<td>IP65 with mating connector mounted and locked</td>
</tr>
<tr>
<td>Control electronics</td>
<td>Integrated in the valve, see page 8</td>
</tr>
</tbody>
</table>

**Connector pin assignment**

<table>
<thead>
<tr>
<th>Contact</th>
<th>Signal with A1</th>
<th>Signal with F1</th>
<th>Signal with A5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage</td>
<td></td>
<td>24 VDC (18 to 35 VDC); (I_{\text{max}} = 1.5 \text{ A}); impulse load (\leq 3 \text{ A})</td>
<td></td>
</tr>
<tr>
<td>B</td>
<td>0 V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Reference (actual value)</td>
<td></td>
<td>Reference potential for actual value (contact &quot;F&quot;)</td>
<td>Enable 4 to 24 V</td>
</tr>
<tr>
<td>Differential amplifier input</td>
<td>±10 V</td>
<td>4 to 20 mA</td>
<td>±10 V</td>
</tr>
<tr>
<td>(Command value)</td>
<td>0 V reference potential to pin D</td>
<td></td>
<td>0 V reference potential for pin D and F</td>
</tr>
<tr>
<td>Measuring output (actual value)</td>
<td>±10 V</td>
<td>4 to 20 mA</td>
<td>±10 V</td>
</tr>
<tr>
<td>PE</td>
<td>Connected to cooling element and valve housing</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Command value:** Reference potential at E and positive command value at D result in flow from P \(\rightarrow\) A and B \(\rightarrow\) T. Reference potential at E and negative command value at D result in flow from P \(\rightarrow\) B and A \(\rightarrow\) T.

**Connection cable:** Recommendation: – Up to 25 m line length: Type LiYCY 7 x 0.75 mm²
– Up to 50 m line length: Type LiYCY 7 x 1.0 mm²
Only connect the shield to PE on the supply side.

**Notice:** Electric signals taken out via valve electronics (e.g. actual value) must not be used for switching off safety-relevant machine functions!
Block diagram of the integrated electronics (OBE)

- Command values
- Pilot current A
- Pilot current B
- Current controller
- Oscillator
- Cable break detection
- Monitoring
- Logic pilot current
- ENABLE 1)
- Reference for output 2)
- Outputs
- Position transducer
- Main stage

Notes:
1) Only available for A5 electronics
2) Only available for A1 and F1 electronics
**Characteristic curves** (measured with HLP46, $\theta_{oil} = 40 \, ^\circ C \pm 5 \, ^\circ C$)

Flow command value function with e.g.
P $\rightarrow$ A / B $\rightarrow$ T 10 bar valve pressure differential or
P $\rightarrow$ A or A $\rightarrow$ T 5 bar per control edge

Control spool E, W, and R

Control spool with characteristic curve L

![Graph](image1)

Control spool with characteristic curve P

![Graph](image2)
**Characteristic curves:** Size 10 (measured with HLP46, $\theta_{oil} = 40 \ ^\circ \text{C} \pm 5 \ ^\circ \text{C}$)

Transition function with stepped electric input signals

[Graph showing signal change in % over time in ms]

Flow/load function with maximum valve opening
(tolerance ±10%)

[Graph showing flow in l/min vs. valve pressure differential in bar]

1 = Recommended flow limitation (flow velocity 30 m/s) in the valve connection bores
**Characteristic curves:** Size 16 (measured with HLP46, $T_{oil} = 40 ^\circ C \pm 5 ^\circ C$)

**Transition function with stepped electric input signals**

![Graph showing transition function with stepped electric input signals.](image)

**Flow/load function with maximum valve opening**

(tolerance ±10%)

![Graph showing flow/load function with maximum valve opening.](image)

1 = Recommended flow limitation (flow velocity 30 m/s) in the valve connection bores
**Characteristic curves:** Size 25 and 27 (measured with HLP46, $\theta_{oil} = 40 \, ^\circ C \pm 5 \, ^\circ C$)

**Transition function with stepped electric input signals**

![Graph showing transition function](image)

**Flow/load function with maximum valve opening**
(tolerance $\pm 10\%$)

![Graph showing flow/load function](image)

1 = Recommended flow limitation (flow velocity 30 m/s) in the valve connection bores
**Characteristic curves**: Size 32 (measured with HLP46, $\theta_{oil} = 40 ^\circ C \pm 5 ^\circ C$)

- **Transition function with stepped electric input signals**

![Graph showing signal change in % vs. time in ms for different stroke in %]

- **Flow/load function with maximum valve opening**
  (tolerance ±10%)

![Graph showing flow in l/min vs. valve pressure differential in bar]

1 = Recommended flow limitation (flow velocity 30 m/s) in the valve connection bores
Characteristic curves: Size 35 (measured with HLP46, ϑ_{oil} = 40 °C ±5 °C)

Transition function with stepped electric input signals

Flow/load function with maximum valve opening
(tolerance ±10%)

1 = Recommended flow limitation (flow velocity 30 m/s) in the valve connection bores
Dimensions: Size 10 (dimensions in mm)

1. Pilot control valve
2. Mating connector "A", color gray
3. Mating connector "B", color black
4. Space required for connection cable and to remove the mating connector
5. Wiring
6. Mating connector, separate order, see page 21
7. Pressure reducing valve
8. Name plate
9. Main valve
10. Integrated electronics (OBE)
11. Identical seal rings for connection A, B, P, T
12. Identical seal rings for connection X, Y
13. Processed valve contact surface, porting pattern according to ISO 4401-05-05-0-05 (connection X, Y, as required)

Subplates and valve mounting screws see page 21
**Dimensions:** Size 16 (dimensions in mm)

1. Pilot control valve
2. Mating connector "A", color gray
3. Mating connector "B", color black
4. Space required for connection cable and to remove the mating connector
5. Wiring
6. Mating connector, separate order, see page 21
7. Pressure reducing valve
8. Name plate
9. Main valve
10. Integrated electronics (OBE)
11. Identical seal rings for connection A, B, P, T
12. Identical seal rings for connection X, Y
13. Processed valve contact surface, porting pattern according to ISO 4401-07-07-0-05 (connection X, Y as required) deviating from the standard:
   - Connection A, B, T and P Ø 20mm
14. Locking pin

Subplates and valve mounting screws see page 21
Dimensions: Size 25 (dimensions in mm)

1 Pilot control valve
2 Mating connector "A", color gray
3 Mating connector "B", color black
4 Space required for connection cable and to remove the mating connector
5 Wiring
6 Mating connector, separate order, see page 21
7 Pressure reducing valve
8 Name plate
9 Main valve
10 Integrated electronics (OBE)
11 Identical seal rings for connection A, B, P, T
12 Identical seal rings for connection X, Y
13 Processed valve contact surface, porting pattern according to ISO 4401-08-08-0-05 (connection X, Y, as required)
14 Locking pin

Subplates and valve mounting screws see page 21
Dimensions: Size 27 (dimensions in mm)

1. Pilot control valve
2. Mating connector "A", color gray
3. Mating connector "B", color black
4. Space required for connection cable and to remove the mating connector
5. Wiring
6. Mating connector, separate order, see page 21
7. Pressure reducing valve
8. Name plate
9. Main valve
10. Integrated electronics (OBE)
11. Identical seal rings for connection A, B, P, T
12. Identical seal rings for connection X, Y
13. Processed valve contact surface, porting pattern according to ISO 4401-08-08-0-05 (connection X, Y as required) deviating from the standard:
   - Connection A, B, T and P Ø 32 mm
14. Locking pin

Subplates and valve mounting screws see page 21
**Dimensions:** Size 32 (dimensions in mm)

1. Pilot control valve
2. Mating connector "A", color gray
3. Mating connector "B", color black
4. Space required for connection cable and to remove the mating connector
5. Wiring
6. Mating connector, separate order, see page 21
7. Pressure reducing valve
8. Name plate
9. Main valve
10. Integrated electronics (OBE)
11. Identical seal rings for connection A, B, P, T
12. Identical seal rings for connection X, Y
13. Processed valve contact surface, porting pattern according to ISO 4401-10-09-0-05 (connection X, Y as required) deviating from the standard:
   - Connection, B, T and P Ø 38 mm
14. Locking pin

Subplates and valve mounting screws see page 21
**Dimensions:** Size 35 (dimensions in mm)

1. Pilot control valve
2. Mating connector "A", color gray
3. Mating connector "B", color black
4. Space required for connection cable and to remove the mating connector
5. Wiring
6. Mating connector, separate order, see page 21
7. Pressure reducing valve
8. Name plate
9. Main valve
10. Integrated electronics (OBE)
11. Identical seal rings for connection A, B, P, T
12. Identical seal rings for connection X, Y
13. Processed valve contact surface, porting pattern according to ISO 4401-10-09-0-05 (connection X, Y as required) deviating from the standard:
   - Connection A, B, T and P Ø 50 mm
14. Locating pins

Subplates and valve mounting screws see page 21
## Dimensions

<table>
<thead>
<tr>
<th>Hexagon socket head cap screws</th>
<th>Material number</th>
</tr>
</thead>
</table>
| **Size 10** | 4x ISO 4762 - M6 x 45 - 10.9-flZn-240h-L  
Tightening torque $M_A = 13.5$ Nm ±10%  
or  
4x ISO 4762 - M6 x 45 - 10.9  
Tightening torque $M_A = 15.5$ Nm ±10% | R913000258 |
| **Size 16** | 2x ISO 4762 - M6 x 60 - 10.9-flZn-240h-L  
Tightening torque $M_A = 12.2$ Nm ±10%  
or  
4x ISO 4762 - M10 x 60 - 10.9-flZn-240h-L  
Tightening torque $M_A = 58$ Nm ±20%  
or  
2x ISO 4762 - M6 x 60 - 10.9  
Tightening torque $M_A = 15.5$ Nm ±10%  
or  
4x ISO 4762 - M10 x 60 - 10.9  
Tightening torque $M_A = 75$ Nm ±20% | R913000115, R913000116 |
| **Sizes 25 and 27** | 6x ISO 4762 - M12 x 60 - 10.9-flZn-240h-L  
Tightening torque $M_A = 100$ Nm ±20%  
or  
6x ISO 4762 - M12 x 60 - 10.9  
Tightening torque $M_A = 130$ Nm ±20% | R913000121 |
| **Size 32** | 6x ISO 4762 - M20 x 80 - 10.9-flZn-240h-L  
Tightening torque $M_A = 340$ Nm ±20%  
or  
6x ISO 4762 - M20 x 80 - 10.9  
Tightening torque $M_A = 430$ Nm ±20% | R901035246 |
| **Size 35** | 6x ISO 4762 - M20 x 100 - 10.9-flZn-240h-L  
Tightening torque $M_A = 465$ Nm ±20%  
or  
6x ISO 4762 - M20 x 100 - 10.9  
Tightening torque $M_A = 610$ Nm ±20% | R913000386 |

**Notice:** The tightening torque of the hexagon socket head cap screws refers to the maximum operating pressure!

## Subplates

<table>
<thead>
<tr>
<th>Size</th>
<th>Data sheet</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>45054</td>
</tr>
<tr>
<td>16</td>
<td>45056</td>
</tr>
<tr>
<td>25 and 27</td>
<td>45058</td>
</tr>
<tr>
<td>32 and 35</td>
<td>45060</td>
</tr>
</tbody>
</table>

## Accessories (not included in the scope of delivery)

<table>
<thead>
<tr>
<th>Mating connectors</th>
<th>Material number</th>
</tr>
</thead>
</table>
| Mating connector for high-response valve | DIN EN 175201-804, see data sheet 08006  
e.g. R900021267 (plastic)  
e.g. R900223890 (metal) |