

# ctrlX I/O

## System and Installation



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DOK-XIO\*\*\*-SYS\*INS\*\*\*\*-AP01-EN-P

DeGr (MaKo/MePe)

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# 1 About this application manual

## 1.1 Revision history

Table 1: Editions of this documentation

Edition	Release date	Note
Edition 01	2024-05	First edition

## 1.2 Scope of validity

This document is valid for all ctrlX I/O modules whose type code starts with:

- XB-xx-xx
- Xlxxxxxx

## 1.3 Related documents

Title	Part number and document type
Security Manual	➔ R911342562
Electric Drives and Controls	Project Planning Manual
ctrlX I/O Modules	➔ ctrlX I/O Data sheets
ctrlX I/O Engineering	Application Description
Field Bus Configuration for ctrlX CORE	Also refer to: ➔ <a href="https://docs.automation.boschrexroth.com/iirds/cdp-metadata.boschrexroth.de~iiDC~Product-ctrlX-I/O-Engineering/">https:// docs.automation.boschrexroth.com/iirds/cdp- metadata.boschrexroth.de~iiDC~Product-ctrlX- I/O-Engineering/</a>

## 1.4 Customer feedback

Customer requests, comments or suggestions for improvement are of great importance. Please email your feedback on the documentations to ➔ [Feedback.Documentation@boschrexroth.de](mailto:Feedback.Documentation@boschrexroth.de). Directly insert comments into the electronic PDF document and send the PDF file to Bosch Rexroth.

## 2 Product identification

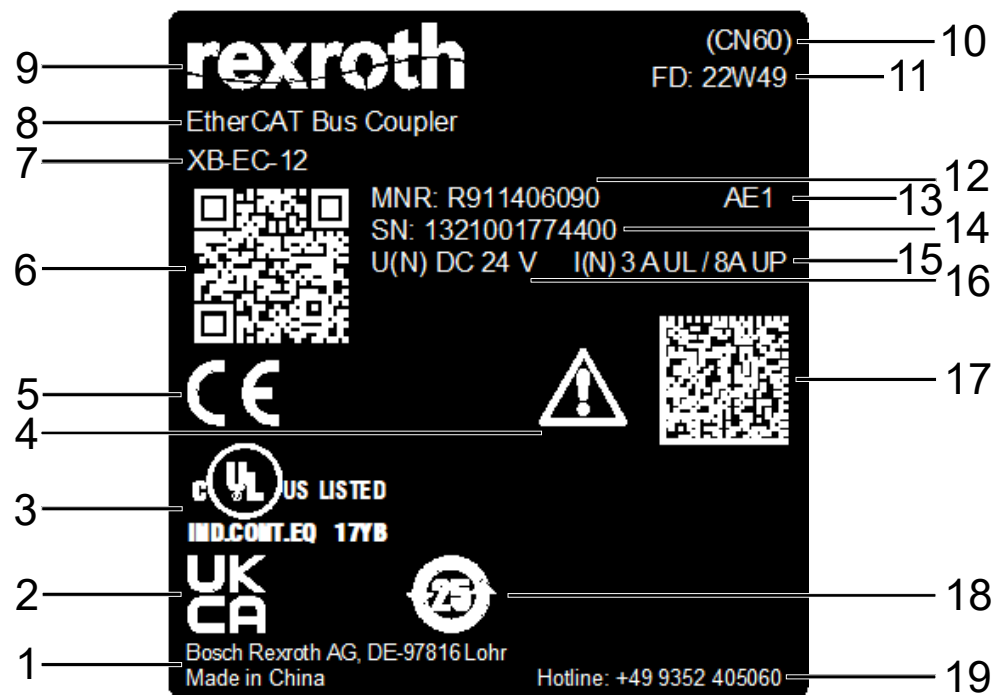


Fig. 1: Type plate (example)

- 1 Company address
- 2 UKCA marking
- 3 Underwriters Laboratories Inc. mark
- 4 Symbol for reference to the operating instructions
- 5 CE conformity mark
- 6 QR or data matrix code, Rexroth, 2D code
- 7 Type code
- 8 Product
- 9 Trademark
- 10 Plant number
- 11 Manufacturing date
- 12 Part number
- 13 State of revision
- 14 Serial number
- 15 Rated voltage
- 16 Rated current
- 17 MAC code (2D code), data matrix
- 18 China-RoHS 2 label
- 19 Service hotline number

## 3 For your safety

### 3.1 User qualification

The product use described in this data sheet is only intended for qualified electricians and staff trained by these qualified electricians. The user has to be familiar with the known safety concepts on automation technology, applicable standards and other guidelines.

## 3.2 Electrical safety

### NOTICE

#### Loss of electric safety

Unintended handling can affect the device safety! Observe the notes in the present data sheet during installation, commissioning and operation.

## 4 Intended use

### NOTICE

#### Risk of damaging the device if not expressly stated accessories, mounting parts and other components, cables, lines, software and firmware are used.

The ctrlX I/O modules may exclusively be used with the accessories and add-on components specified in this documentation. Components that are not expressly mentioned must neither be attached nor connected. The same applies to cables and lines.

Operation must only be carried out with the hardware component configurations and combinations that are expressly specified.

Typical areas of application of the modules:

- Handling and assembly systems
- Packaging and food processing machines
- Printing and paper converting machines
- Machine tools
- Wood working machines
- General mechanical engineering
- Building automation

### ⚠ WARNING

#### Danger due to unintended use

The protection specified by Bosch Rexroth cannot be ensured if not used as intended.

- Use the product exclusively as intended by Bosch Rexroth.
- Operate this device only under the mounting and installation conditions, in the position and under the ambient conditions (temperature, degree of protection, humidity, EMC etc.) specified in the respective data sheet.

## 5 ctrlX product group

### 5.1 ctrlX I/O - Modular I/O system

With ctrlX I/O from Bosch Rexroth, there are completely new options for connectivity and networking. The I/O portfolio is used for horizontal and vertical integration and also represents a functional extension of the ctrlX CORE control platform. This provides users with comprehensive communication and performance extensions, as well as I/O modules with regard towards future technologies such as 5G, TSN and AI.

Key features of ctrlX I/O at a glance:

- Compact: 50% less control cabinet requirement
- Flexible and unlimited topologies
- EtherCAT up to the module



- Quick and easy commissioning
- Perfectly matched to ctrlX CORE
- Future-proof
- Integrating own modules

## 5.2 Design of a ctrlX I/O station

A ctrlX I/O station consists of individual modules snapped onto an earthed support rail. The head of the station is a control or a bus coupler. The I/O modules are connected to the control or the bus coupler. The individual modules are connected to each other and to the station head using an integrated jumper plug.

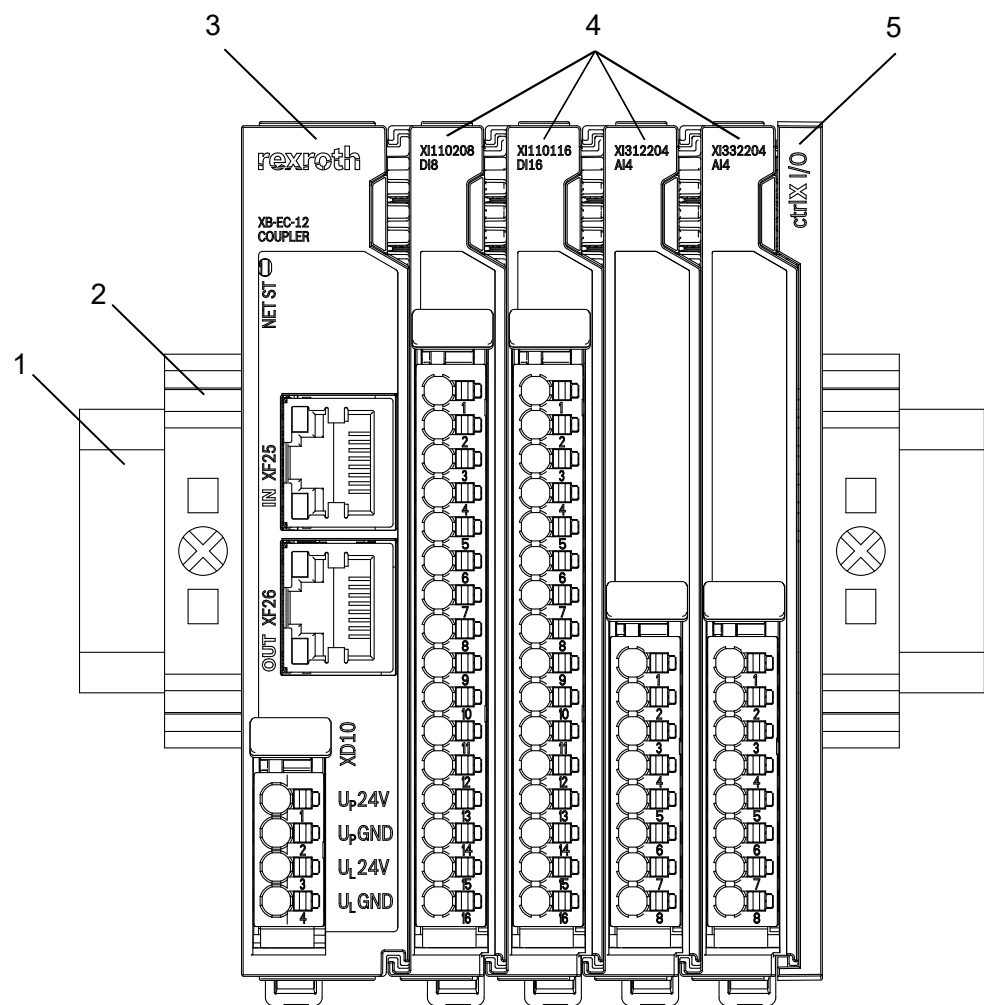


Fig. 2: Design of a ctrlX IO station

- ① Support rail
- ② End clamps (to fix the station)
- ③ EtherCAT bus couplers
- ④ ctrlX I/O input or output modules
- ⑤ Endcover



For detailed information on function, properties, wiring and parameterization, refer to the module-specific documentation.

## 5.3 Product description

I/O modules with various functions are available within the ctrlX I/O product group.

The ctrlX I/O modules consist of an electronic module and a peripheral plug.

The well thought-out ergonomic mechanical design and push-in technology enable simple tool-free installation and quick replacement of modules without having to disconnect a conductor from the peripheral plug.

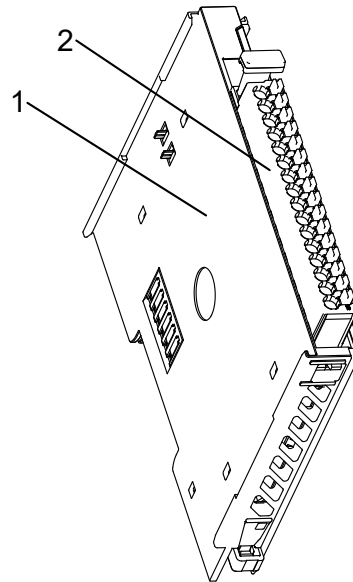


Fig. 3: Exemplary module, 12 mm

- ① Electronics module
- ② Peripheral plug

## 6 ctrlX devices at a glance

### 6.1 ctrlX CORE control

The ctrlX CORE compact control in embedded format is suitable for the support rail mounting and for its use in a control cabinet.

The various ctrlX CORE models are available in several performance classes and provide sufficient computing power for the most demanding control tasks. The Linux-based operating system is open for the integration of all ctrlX CORE Runtime and ctrlX CORE Engineering apps from the ctrlX WORKS function module kit and other further customized apps. A central ctrlX Data Layer is used to exchange the communication between the apps in realtime and non-realtime.

The onboard EtherCAT master is used to connect and control the drives, I/O modules and other devices from the open EtherCAT ecosystem.

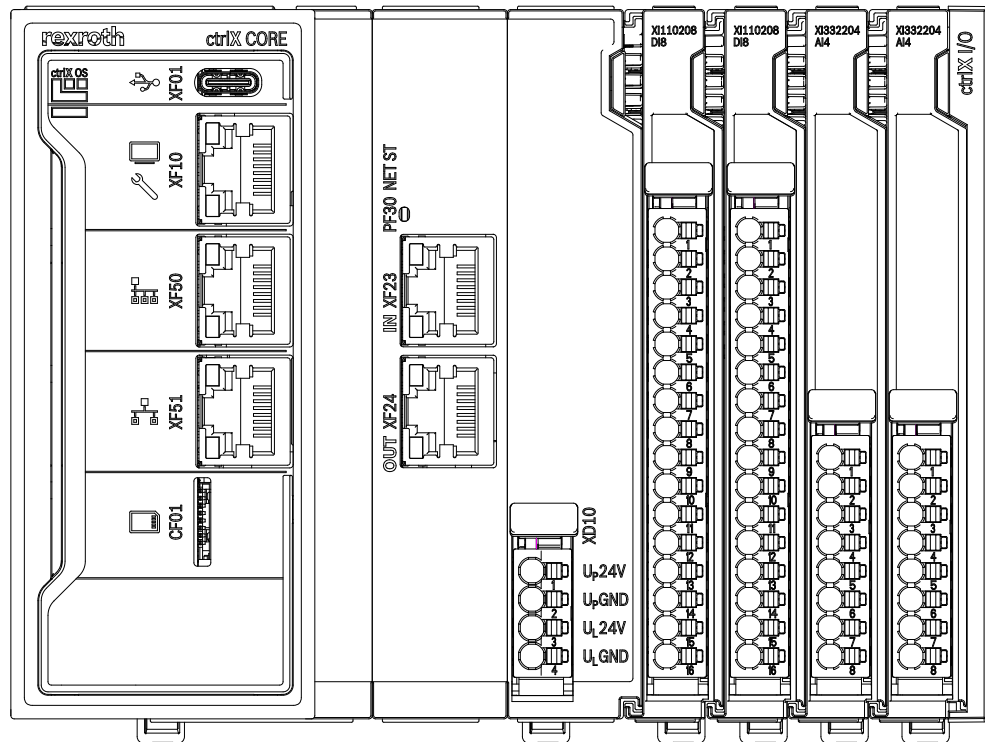


Fig. 4: Device overview, ctrlXCOREplus X3, including I/O modules

## 6.2 EtherCAT bus coupler

The bus coupler XB-EC-12 connects the EtherCAT network and the ctrlX I/O system. The bus coupler supplies the connected I/O modules with the logic voltage  $U_L$  and the peripheral voltage  $U_P$ .

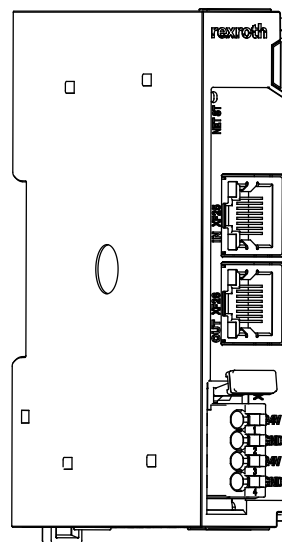


Fig. 5: EtherCAT bus couplers

## 6.3 Input and output modules

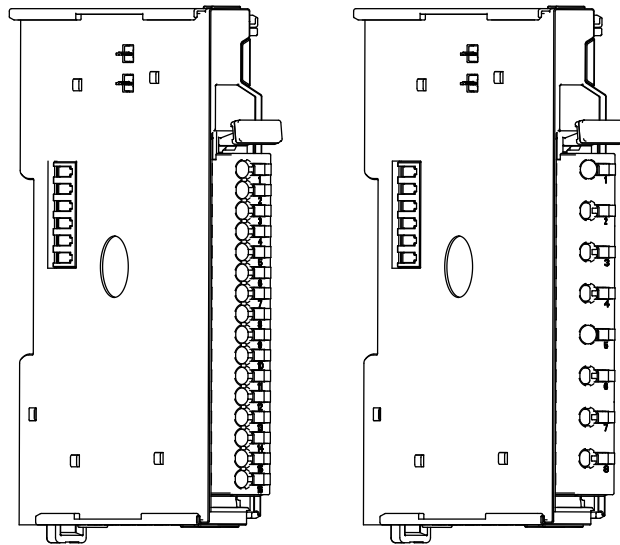


Fig. 6: Exemplary view DO16 and DOR2

The ctrlX I/O modules provide the interface function for the system, e.g. the following:

- Digital input and output modules
- Analog input and output modules
- Communication modules
- Function modules

The modules listed are active modules, i.e. they are EtherCAT devices. Process data is therefore exchanged via the local bus.

## 6.4 System modules XI8

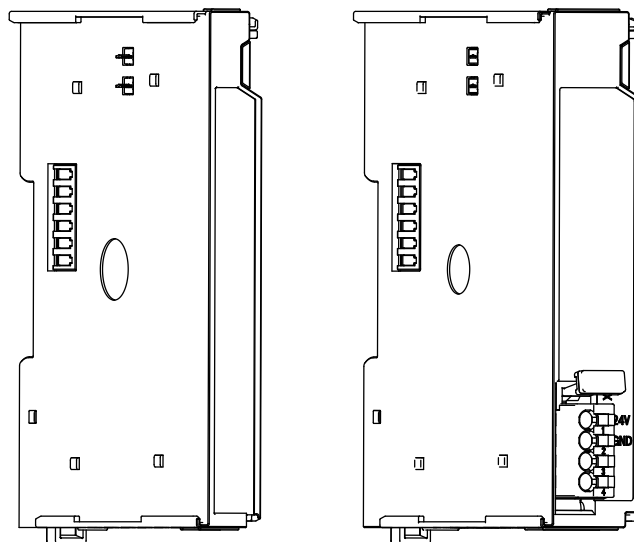


Fig. 7: 12 mm empty housing terminal 20 mm boost terminal

System modules provide specific functions within a ctrlX I/O station:

- Voltage boost or segmentation
- Potential distribution
- Empty housing

Some of the modules listed are passive modules, i.e. they are not EtherCAT devices and therefore do not exchange process data. Please refer to the product-specific data sheet.

## 6.5 ctrlX I/O module types and article name

	Name	Detailing	Example
XB-xx-xx	Bus modules	EtherCAT Bus Coupler or decoupling, number of ports	XB-EC-12 EtherCAT Bus coupler
XI1xxxxx	Digital input modules	4-, 8-, 16-channel PNP, NPN, counter, time-stamping or oversampling DC 24 V 1-, 2-wire	XI110116 16Ch. Dig. Input 24V 3ms
XI2xxxxx	Digital output modules	4-, 8-, 16-channel PNP, NPN, relay, PWM or oversampling DC 24 V 1-, 2-wire	XI210116 16Ch. Dig. Output 24V/0.5A
XI3xxxxx	Analog input modules	4-channel Measuring range Resolution	XI312204 4Ch. Ana. Input 0-10V 16Bit
XI4xxxxx	Analog output modules	2-, 4-channel Output range Resolution	XI412204 4Ch. Ana. Output 0-10V 16Bit
XI5xxxxx	Communication modules	1-, 2-, 4-channel IO-Link, RS485, RS232, MBUS	XI521001 1Ch. Serial RS232
XI6xxxxx	Function modules	Encoder interface	XI613101 1Ch. Encoder Inc TTL
XI8xxxxx	System modules	Voltage boost, potential distribution	XI821116 16Ch. Potential distribution GND

## 7 Voltage concept

A ctrlX I/O station consists of at least one voltage-supplying module (bus coupler or ctrlX CORE<sup>plus</sup>) and multiple consumers (I/O modules).

There are two main power supply rails:  $U_L$  for the logic supply and  $U_P$  for the peripheral supply.  $U_L$  and  $U_P$  are galvanically isolated from each other.

Current is supplied centrally via a ctrlX I/O bus coupler or a boost module. Refer to the module-specific documentation. The circuitry of a station always has to be closed. The circuitry starts and ends at the same voltage-feeding module. No other voltage sources may be connected to the circuitry!

The  $U_L$  logic supply (24 V) is filtered and passed through to the I/O modules on the right. Depending on the power consumption of the connected modules, the  $U_L$  logic supply is sufficient for up to 30 modules.  $U_L$  has then be fed in again via a boost module (XI813101). The  $U_L$  backfeeding has to provided by power supply unit like the  $U_L$  backfeeding at the bus coupler or at the control.

The peripheral supply  $U_P$  is filtered and then fed to the I/O modules. The input has no internal protection against overcurrent. Up to 8 A per station can be drawn from the pins  $U_{OUT}$  24 V and GND without a new peripheral backfeeding.

**NOTICE****Electronic damages**

An overcurrent protective device with a maximum rating of 10 A must be fitted when the device is installed, e.g:

- main circuit breaker to UL489(\*) (B-, C-, D-, K- or Z-characteristics)
- Class CC or Class J fuse acc. to UL248(\*)

The overcurrent protective devices marked with "\*" should be used in installations conforming to UL standards.

## 7.1 Segmentation

Multiple segments with galvanically isolated peripheral supply areas can be created using a voltage supply boost terminal for the peripheral circuit, which is connected to an isolated current supply.

An external overcurrent protection device is required for each  $U_P$  segmentation!

## 7.2 Multi-wire technique

The multi-wire technique provides  $U_{OUT}$  24 V and  $U_{OUT}$  GND in various extension stages.  $U_{OUT}$  24 V is the filtered peripheral supply potential  $U_P$  24 V.  $U_{OU}$  GND is the filtered peripheral reference potential  $U_P$  GND.



- The  $U_{OUT}$  24 V outputs are only to be used as switching potential to the respective input.
- These outputs may not be used as peripheral voltage supply.
- To supply the connected actuators, use the potential distribution terminals, e.g. XI822116.

## 7.3 GND-FE binding

There is no direct GND-FE binding. GND is only connected to FE via a resistor and capacitor network.

## 8 Housing variants, design and dimensions

### 8.1 Basic design

#### 8.1.1 EtherCAT bus coupler

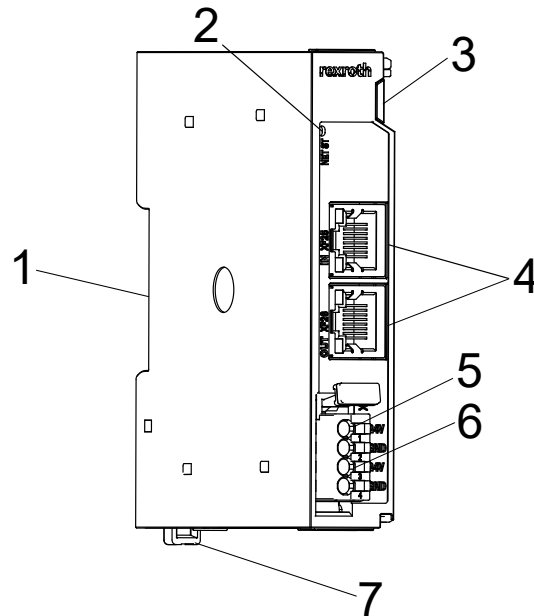


Fig. 8: XB-EC-12

- ① Support rail holder
- ② PF30 NET ST LED
- ③ Module status display
- ④ EtherCAT interfaces: IN (XF25) and OUT (XF26)
- ⑤ Voltage supply U<sub>P</sub>
- ⑥ Voltage supply U<sub>L</sub>
- ⑦ Locking lever

### 8.1.2 I/O module

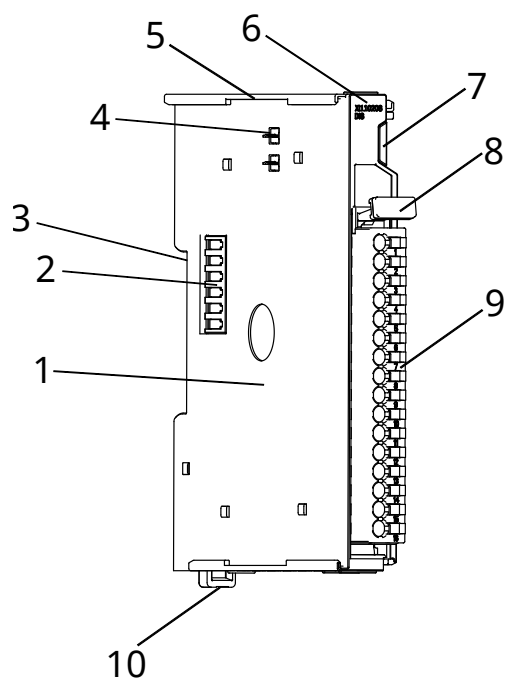


Fig. 9: Electronic module 12 mm

- ① Electronics module
- ② Patch connector
- ③ Support rail holder
- ④ Power contacts
- ⑤ Guide rail
- ⑥ Type code and short name
- ⑦ Module status display
- ⑧ Locking lever
- ⑨ Peripheral plug
- ⑩ Locking lever



### 8.1.3 Support rail holder

The support rail holder is identical for all ctrlX I/O modules.

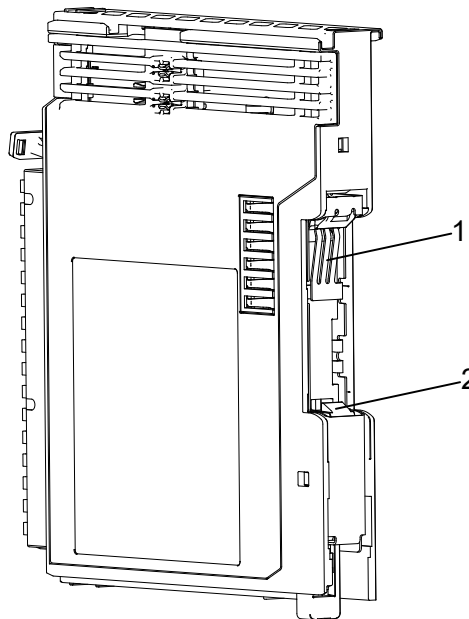


Fig. 10: Support rail holder and FE connection

- ① FE connection
- ② Engagement of the support rail holder

## 8.2 Dimensions of the ctrlX I/O modules

All following dimensions are given in mm.

### 8.2.1 EtherCAT bus coupler

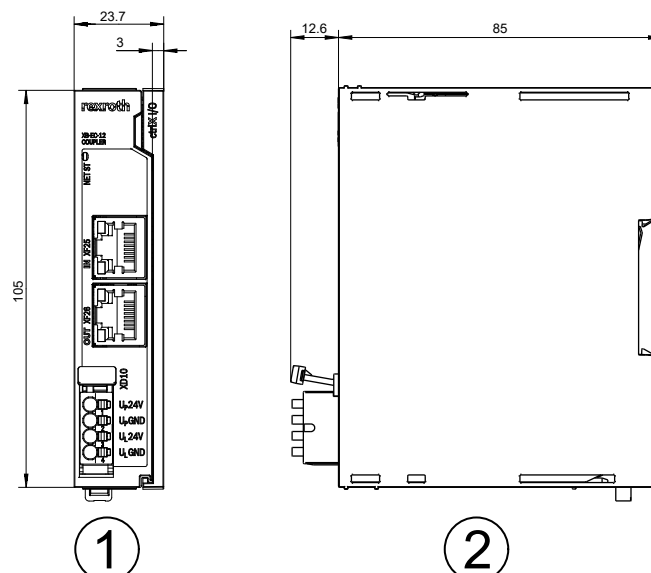


Fig. 11: Bus coupler with endcover

- ① Front view  
② Side view

## 8.2.2 12 mm and 20 mm modules

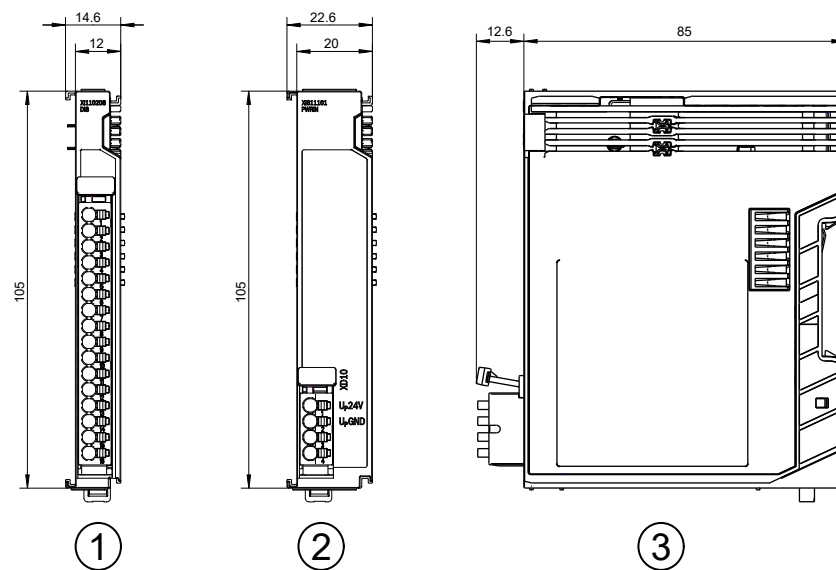


Fig. 12: 12 mm module and 20 mm module

- ① Front view of the 12 mm module
- ② Front view of the 20 mm module
- ③ Side view

## 8.3 Peripheral plug

### 8.3.1 Basic design

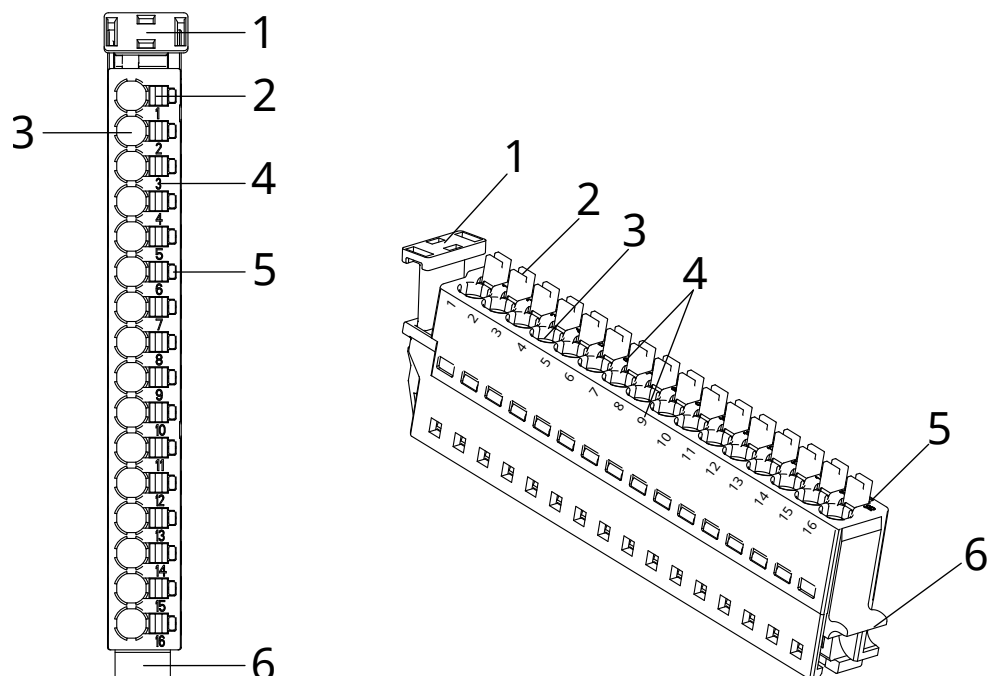









Fig. 13: Design of the peripheral plug

- ① Locking lever
- ② Pusher
- ③ Clamping point
- ④ Clamping point labeling

- ⑤ Status display
- ⑥ Rotary axis

### 8.3.2 Pusher colors

Color	RAL color	Function of the clamping point
 Light gray	RAL 7035	Function clamping point
 Red	RAL 3020	Voltage supply 24VDC
 Blue	RAL Design 230 50 35	Voltage supply GND
 Dark red	RAL 3003	U <sub>OUT</sub> DC 24 V (more exact function depends on the module)
 Dark blue	RAL Design 240 20 22	U <sub>OUT</sub> GND (more exact function depends on the module)
 Green	RAL Design 130 60 40	FE
 Yellow	RAL 1018	Safety function clamping point

### 8.3.3 Variants and dimensions

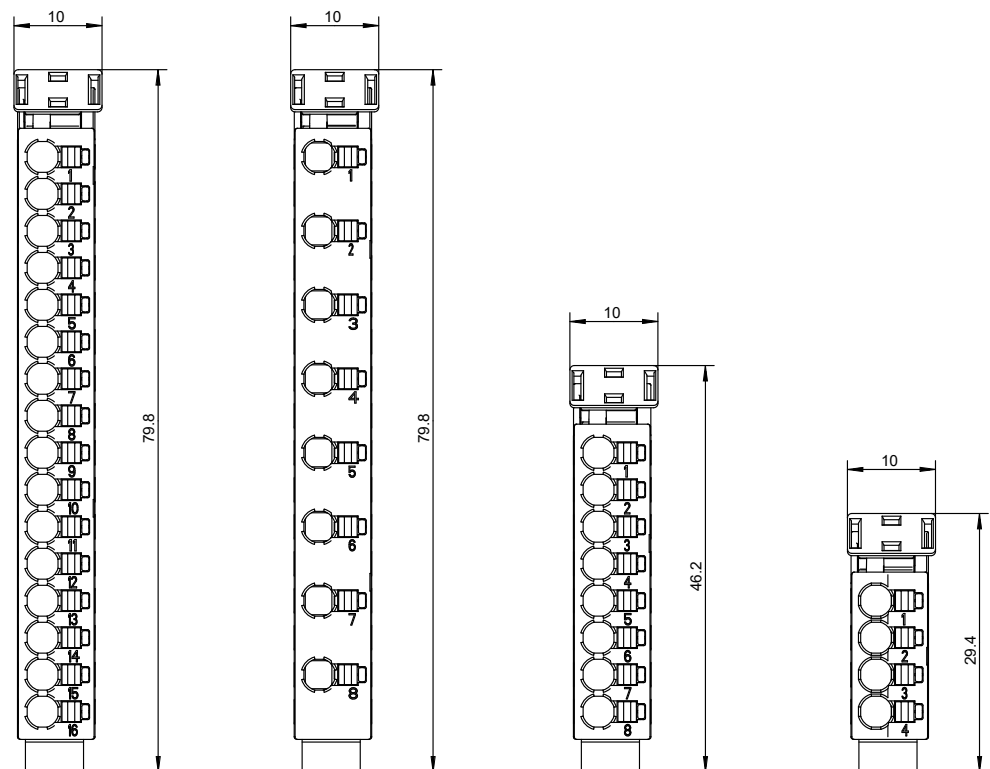


Fig. 14: Dimensions of various peripheral plugs

## 9 Transporting, storing and unpacking

### 9.1 Transporting

**NOTICE****Electrostatic discharge!**

Electrostatic discharge can damage or destroy components. Comply with the required safety measures against electrostatic discharge (ESD) acc. to EN 61340-5-1 and IEC 61340-5-1 when handling the module.

ctrlX I/O modules are packaged in a folding box. Observe the handling instructions on the packaging.

Only transport the modules in their original packaging or in packaging suitable for transportation.

During transportation, observe the information in the product-specific data sheet regarding humidity and temperature range.

### 9.2 Storing

The storage location has to meet the following conditions:

- Dry
- Protected from external influences
- Protected from harmful environmental influences such as UV light

When storing, observe the information in the product-specific data sheet in the technical data on environmental conditions such as temperature range, air pressure and humidity.

### 9.3 Unpacking

Read the package insert carefully before installing and using the device. Keep the package insert in a safe place.

Check the delivery for damage and completeness. Make a complaint about any transport damage immediately.

Product insert

- Scope of delivery for the bus coupler:  
ctrlX I/O bus coupler with attached peripheral plug, mounted endcover and package insert.
- Scope of delivery for a standard module:  
ctrlX I/O module with attached peripheral plug (if available) and package insert.

## 10 Module mounting

### 10.1 Basic information on mounting

Note the following mounting instructions

- Module sequence:  
You can connect the ctrlX I/O modules to the bus coupler in any order within a segment circuit. To ensure the function, connect the modules in series without gaps.  
If you are using modules with a shield connection, we recommend installing them next to each other to optimally use the busbar for the shield connection, see also [Chapter 12 Grounding and shielding on page 28](#).
- Maximum number of modules:

The maximum number of ctrlX I/O modules within a station without back-feeding the logic voltage  $U_L$  is 30. For larger stations, a backfeed of the logic voltage  $U_L$  has to be used, even if the available logic current has not yet been used up.

The following factors can limit the actual number of modules within a ctrlX I/O station:

- The provided logic current.
- The current consumption of the connected modules.
- The system limits of the bus coupler.

See also [Chapter 7 Voltage concept on page 13](#).

- Current supply and current consumption:

The bus coupler supplies the current supply for the local bus  $U_L$  and the peripheral supply  $U_P$ . The total current consumption of  $U_L$  and  $U_P$  of all ctrlX I/O modules supplied in the station must not exceed the maximum currents according to the module-specific data sheet of the power supply (bus coupler, boost module). The current consumption of the logic and peripherals are specified for each module in the module-specific data sheet as "Current consumption  $U_L$ " and "current consumption  $U_P$ ".

When the maximum current consumption is reached, use a boost module, see also [Chapter 7 Voltage concept on page 13](#).

- Maximum number of mating cycles

The ctrlX I/O modules are designed for up to 50 mating cycles for peripheral plugs, patch connectors, power plugs and FE contacts. In addition, contact problems can result, which can also be caused by corrosion of the damaged contact points over a longer period of time.

#### NOTICE

##### Damaging contacts

Mechanical overstress of the clamping points can damage them.  
Provide strain relief for the connected cables.

## 10.2 Installation notes

#### NOTICE

##### Device destruction due to electrostatic discharge

The device contains components that can be damaged or destroyed by electrostatic discharge. Comply with the required safety measures against electrostatic discharge (ESD) acc. to EN 61340-5-1 when operating the module.

- Mounting location

The module has the degree of protection IP 20 and is thus intended for use in a closed control cabinet or control box (terminal box) with the degree of protection IP 54 or higher. The control cabinet fulfills the function of the final safety enclosure. The modules must be installed in the final safety enclosure. They have to be provided with sufficient rigidity according to UL 61010-1, 61010-2-201 and have to meet the requirements with regard to fire propagation.

- End clamps

Fasten end clamps of the type SUP-M01-ENDHALTER (R911170685) on both sides of the station. End clamps ensure the correct fastening on the support rail and are used as lateral end elements. Always fasten one end clamp of the station before mounting the station. This ensures the following:

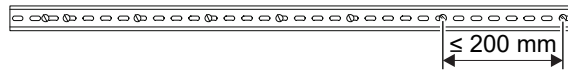
- It impedes the shifting of the modules
- The installation place for the end clamps is secured.

- Endcover

At the end of each ctrlX I/O station, slide an endcover of type XACC-2-END-COVR onto the last module. The endcover is included in the scope of delivery of the bus coupler. Sliding on the endcover ensures protection against accidental contact.

- Support rail

Mount the module on a 35 mm standard support rail. Only use a support rail TH 35-7.5 acc. to EN 60715. The fastening distance of the support rails may not exceed 200 mm. This distance is required to ensure stability while mounting and dismantling the module.



- Provide the following minimum distances for sufficient cooling:

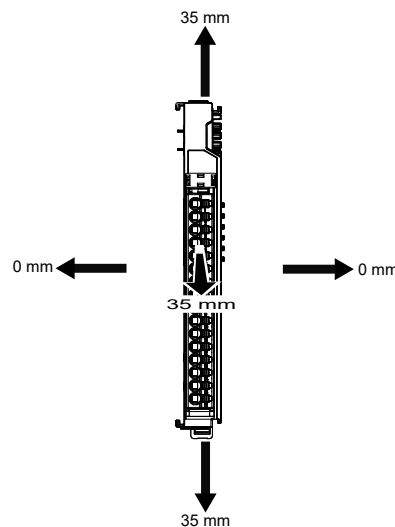


Fig. 15: Ventilation distance

- Additionally, provide sufficient distance for mounting, dismantling, plugs and cables.
- If more devices are connected in series to the station on the left or right, the surface temperature may not exceed 60° C
- In case of a several line design, the supply air has to be measured under each line and its limit value may not be exceeded. For permitted values, refer to the chapter "Ambient conditions" of the respective module data sheet.

### 10.3 Maximum number of passive terminals

Passive terminals are not devices at the local bus. This means that the bus signals are not processed in these terminals.



To ensure the transmission quality, up to three passive modules may be plugged in one after the other. After that, at least one active terminal with a local bus device has to be installed again before the next passive terminal may be set.

### 10.4 Mounting the ctrlX I/O module

#### NOTICE

#### Damage of the device by plug mounting under voltage!

Disconnect the module and all connected module components from voltage before mounting or dismantling.

<b>NOTICE</b>	<b>Damage of the device by short circuit of patch connectors</b>
	There is an endcover on the right upon delivery of the bus coupler. Remove this endcover to connect the modules at the bus coupler in series. Position the endcover on the last module of the station to protect it against short circuit and contamination.
<b>NOTICE</b>	<b>Possible damage to property due to unintended mounting of the support rail</b>
	<ul style="list-style-type: none"> <li>- Connect the support rail to a functional earth.</li> <li>- Mount the module on a support rail.</li> <li>- Install the module in a control cabinet or in an appropriate housing.</li> </ul>
<b>NOTICE</b>	<b>Module is not fixed correctly due to open support arm mounting!</b>
	Before mounting, ensure that the support arm mounting of the control is not clamped in open position. If required, release the clamping using the locking lever as shown in the following figure.

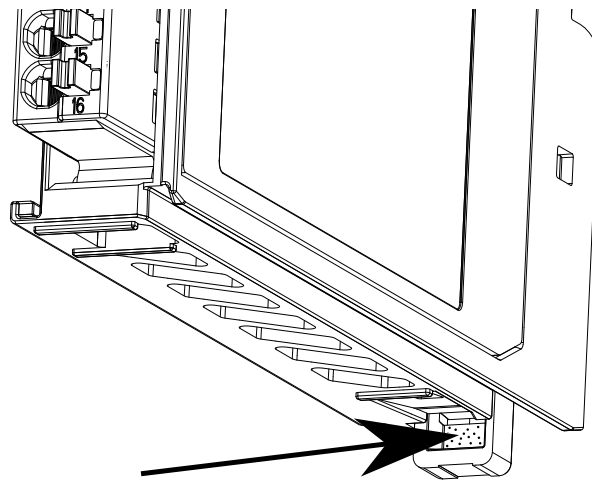


Fig. 16: Locking lever to release the clamping of the open position.  
Each module has to be snapped separately.

## 10.5 Positioning peripheral plug

1. ➤ Position the peripheral plug on the peripheral plug holder, see ①.
2. ➤ The peripheral plug engages at the locking lever, see ②

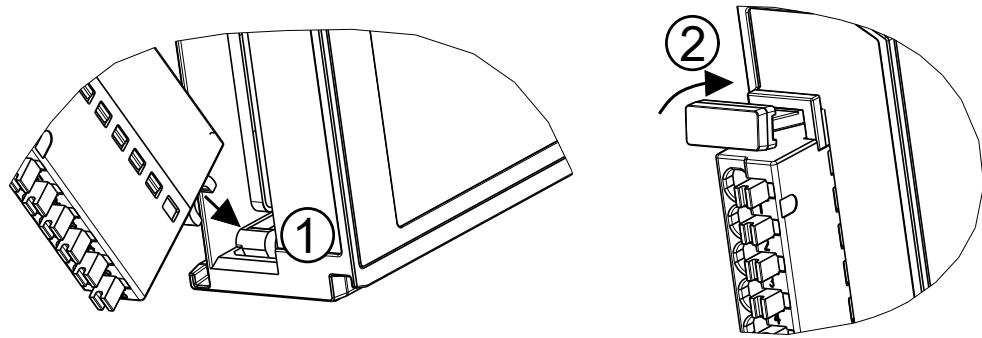


Fig. 17: Positioning peripheral plug

## 10.6 Removing peripheral plug

1. ➤ Press the locking lever of the peripheral plug, see ①.
2. ➤ Remove the peripheral plug, see ②.

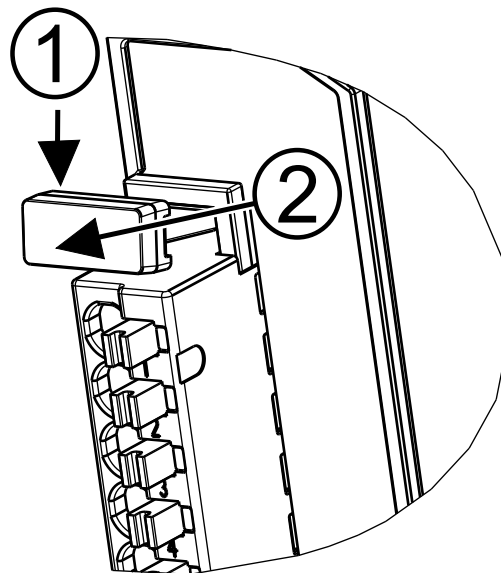


Fig. 18: Removing peripheral plug

## 10.7 Dismounting the module



For dismounting, use a common tool such as a slotted screwdriver with a 2.5 mm blade.

### NOTICE

**Destruction of components and devices due to mounting and dismounting under voltage!**

Disconnect the module and all connected module components from voltage before mounting or dismounting.

### Removing module from support rail

1. ➤ Use a suitable tool (e.g. slotted screwdriver) and put it into the lower disengaging mechanism (base latch) of the module and disengage the module (see (A) in the following figure). The base latch is locked in the open position.
2. ➤ Remove the module vertically to the support rail [see (B) in the following figure].



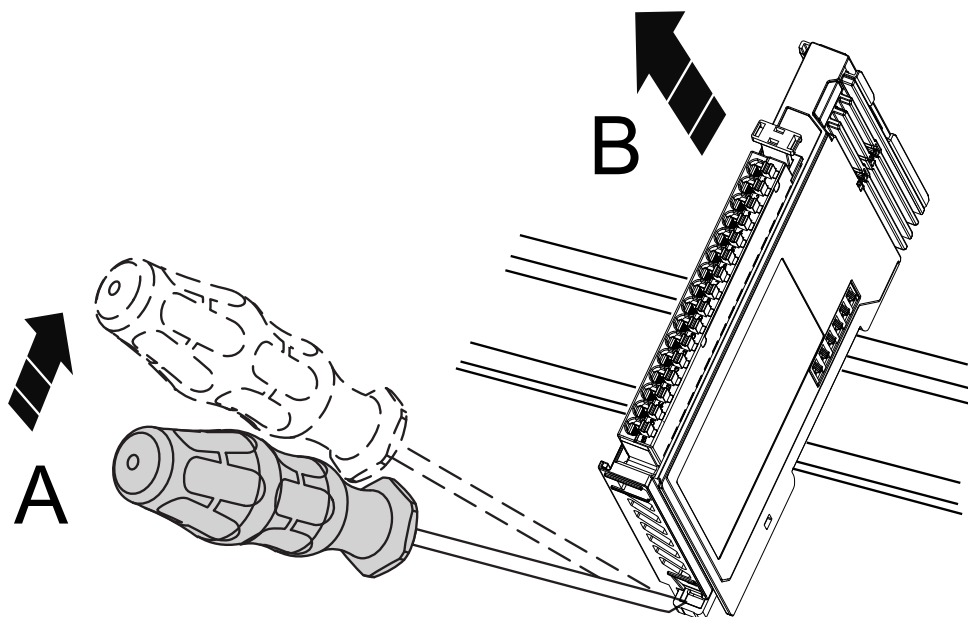


Fig. 19: Dismounting module



Before mounting the module on the support rail again, release the clamping of the open position again. Press the locking lever, refer to the figure Fig. 16.

## 11 Electric installation

### 11.1 Notes on the electrical connection

- To avoid EMC interferences due to loop formation, 24 V voltage potential and ground (GND) have to be connected in star shape from the 24 V power supply unit to the connections for logic voltage ( $U_L$ ) and peripheral voltage ( $U_P$ ).

#### 11.1.1 Tools

- Use the "Phoenix Crimpfox 6" crimping plier to crimp wire end ferrules. The ordering number is: "1212034 Crimpfox 6" at Phoenix Contact.
- Use a slotted screwdriver with a 2.5 mm blade.

#### 11.1.2 Permitted lines

- Rigid lines  
Stripping length: 8.5 mm  $\pm$  0.5 mm, burr-free
- Flexible line without wire end ferrule  
Stripping length: The length of the stripped and 360° twisted braids has to be 8.5 mm  $\pm$  0.5 mm
- Flexible line with wire end ferrule
- Use a cable cross-section corresponding to the current (minimum 0.2 mm<sup>2</sup>, maximum 1.5 mm<sup>2</sup>) to avoid an excessive increase in temperature. A cable cross-section of 1.5 mm<sup>2</sup> is specified for the power supply ( $U_P$ ) of 8 A. The minimum cable cross-section for the power supply ( $U_L$ ) is 0.75 mm<sup>2</sup>.
- The insulation of the cables used has to correspond to the rated voltage.

### 11.1.3 Wire end ferrules

- Wire end ferrules with and without insulating collar are permitted with a contact length of 8 mm according to DIN 46228.
- Maximum dimensions of the crimped wire end ferrule:  
Height 1.45 mm  
Width 2.34 mm
- Twin wire end ferrules are not permitted.

### 11.1.4 Orientation of the wire end ferrules

- The orientation of the wire end ferrule in the clamping point has to be vertical.

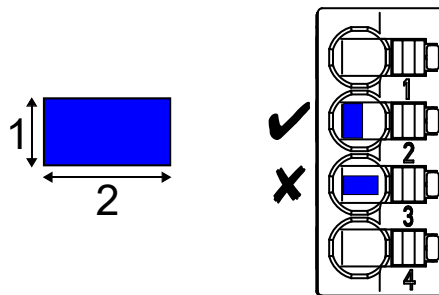


Fig. 20: Orientation of the wire end ferrules in the clamping point

- 1 Height of the crimped wire end ferrule
- 2 Width of the crimped wire end ferrule

### 11.1.5 Installing lines

- Press the pusher with a suitable slotted screwdriver.
- Insert the line into the clamping point as far as possible.
- Release the pusher.

### 11.1.6 Uninstalling lines

- Press the pusher with a suitable slotted screwdriver.
- Remove line.
- Release the pusher.

### 11.1.7 Mounting notes for UL certification

#### Permitted lines

- Use flexible lines with wire end ferrules for UL devices.
- The following wire end ferrules are permitted:
  - Wire end ferrules with insulating collar as per the table:

Cable cross-section in AWG	Cable cross-section mm <sup>2</sup>	Ordering numbers of the wire end ferrules (Weidmüller company)
24 AWG	0.2 mm <sup>2</sup>	9025760000, 500 pieces
22 AWG	0.35 mm <sup>2</sup>	9025770000, 500 pieces
20 AWG	0.5 mm <sup>2</sup>	0690700000, 500 pieces 1476230000, 100 pieces
18 AWG	0.75 mm <sup>2</sup>	0462900000, 500 pieces 1476240000, 100 pieces

-	1 mm <sup>2</sup>	0463000000, 500 pieces 1476250000, 100 pieces
16 AWG	1.5 mm <sup>2</sup>	0463100000, 500 pieces 1476270000, 100 pieces

### Orientation of wire end ferrules

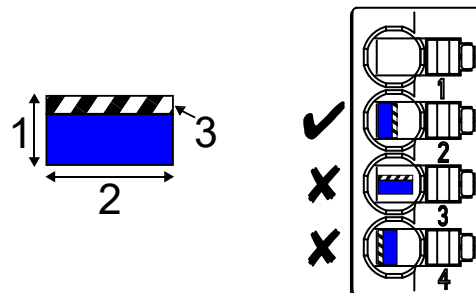


Fig. 21: Orientation of the wire end ferrules in the clamping point

- 1 Height of the crimped wire end ferrule
- 2 Width of the crimped wire end ferrule
- 3 Crimped side of the wire end ferrule

## 11.2 Connecting the voltage supply

The voltage supply for logic and peripherals is provided via the front connector. Logic and peripheral voltages are galvanically isolated internally. Both inputs have reverse polarity protection.

### 11.2.1 Logic voltage supply

The logic voltage and logic current are monitored in the bus coupler. The measured values are provided via the EtherCAT bus.



In case of overvoltage or undervoltage of  $U_L$ , all modules connected to the segment circuit are switched off.

### 11.2.2 Peripheral voltage supply

The peripheral voltage is measured in the bus coupler and forwarded directly to the I/O modules. The input has no internal protection against overcurrent.

#### NOTICE

#### Electronic damages

An overcurrent protective device with a maximum rating of 10 A must be fitted when the device is installed, e.g:

- main circuit breaker to UL489(\*) (B-, C-, D-, K- or Z-characteristics)
- Class CC or Class J fuse acc. to UL248(\*)

The overcurrent protective devices marked with "\*" should be used in installations conforming to UL standards.

## 11.3 Connecting EtherCAT network to the bus coupler

Connect the EtherCAT to the bus coupler via an 8-pin plug.

The EtherCAT connections are direction-dependent.

Name	Direction	Note
XF25	IN	Line connection from the direction of the master.
XF26	OUT	Line connection in the direction of further slaves.



Autocrossover

Both Ethernet interfaces are provided with the "Autocrossover" function.



Shielding

The shield of the connectable twisted-pair wires is electroconductive and connected to the socket. When connecting net segments, avoid ground loops, accidental energization and potential equalization currents via the shielding braid.



Observe bending radii

The housing dimensions under "Dimensions" refer to the bus coupler with peripheral plugs without Ethernet connection. When installing the bus coupler into a control cabinet, observe the bending radii of the Ethernet cables and the plug connectors used.

To observe the bending radii, use angled RJ45 plugs.



Installing Ethernet cable

The Ethernet cable must not be installed or routed outside the building.

Table 2: EtherCAT interface

Connection method	RJ45 socket ("autonegotiation" and "autocrossing")
Transmission rate	100 MBit/s (full duplex)
Cycle time	125 us min., 10 ms max.
Transmission physics	Ethernet in RJ45-Twisted-Pair
Transmission length	100 m max.

## 12 Grounding and shielding

### 12.1 Grounding

#### **NOTICE**

#### **Failure due to insufficient grounding**

An optimum grounding is required to impede possible interferences from the I/O modules and to discharge them to the ground.

#### 12.1.1 Functional earth (FE)



Only the functional earth (FE) is used for the device. The functional earth is only used to discharge disturbances. For individuals, the functional earth is not intended as protection against electric shock.

The ctrlX I/O modules are grounded via the support rail. The support rail, on which the ctrlX modules are mounted, has to be mounted to a grounded metal carrier, e. g. the rear panel of the control cabinet.

The individual ctrlX I/O modules have FE springs (metal clips) on the rear, which create an electrical connection to the support rail during installation. The support rail has to be grounded. If required, it has to be provided with a separate grounding connection.

To ensure reliable functional earthing, ensure a correct installation, see [Chapter 10.1 Basic information on mounting on page 20](#).

## 12.2 Shielding

### NOTICE

#### Failure due to insufficient shielding

Provide sufficient shielding.

The shielding reduces any effects of interferences on the system.

Check the module-specific data sheet to see whether shielding is required.

Observe the following when shielding:

- Attach the shield as large as possible.
- Ensure proper contact between connector and module.
- Avoid damaging or squeezing conductors.
- Note the wire specifications when connecting the shielding.
- Shield the closest possible to the signal clamping points. The signal cables should be routed the shortest possible without shielding.
- Connect the cable shielding to the functional earth immediately after entering the control cabinet. Route the cable with its shielding up to the module.



Route all power cables and data cables in separate cable channels.

### 12.2.1 Shield set

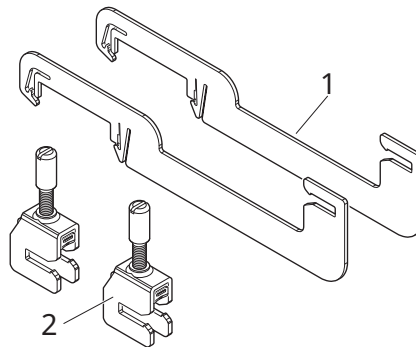


Fig. 22: Shield set

- ① Shield rail holder (2 pieces)
- ② SK 5 shield connection clamps to attach the busbar to the shield rail holder (2 pieces)

For the best connection of the shielding directly in front of the module, the shield connection set (R911173030) is provided together with the busbar (R911173283).

The shields are connected to the busbar with shield clamps (both accessories).

## Mounting

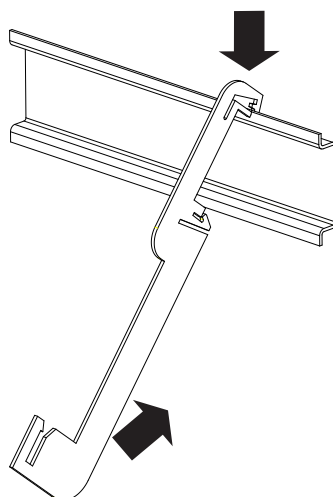


Fig. 23: Engaging shield set

Mount the shield rail holders after mounting the ctrlX I/O modules.

Ensure that the endcover was pushed onto the last module before fitting the shield rail holder.

- Engage the shield rail holder.
- Engage the shield rail holder on the support rail.

## Dismounting

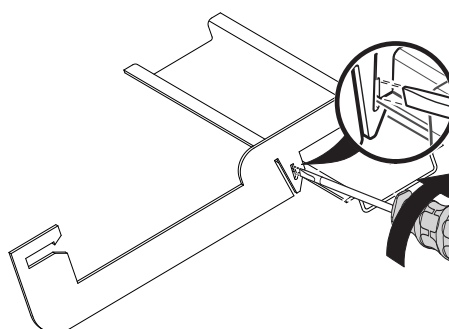


Fig. 24: Loosening shield set

Use a screwdriver with a 4 mm blade width for dismounting purposes.

- First remove the neighboring modules.
- Insert the screwdriver into the unlocking slot.
- Turn the screwdriver so that the snap hook is released from the support rail.
- Remove the shield rail holder.

# 13 Spare parts and accessories

## 13.1 RJ45 cable

Ordering code	Part number	Description
RKB0020	R911340676	Bus cable

## 13.2 End clamp

Ordering code	Part number	Description
SUP-M01-END-HALTER	R911170685	2 pieces of snap-on end brackets for 35 mm NS 35/7.5 support rail; width: 9.5 mm

## 13.3 End cover

Ordering code	Part number	Description
XACC-2-ENDCOVR	R911412178	End cover

## 13.4 Shield connection

Part number	Description
R911173030	Shield connection set, 1 piece, includes 2 shield rail holders and 2 SK 5 shield clamps
R911173282	Shield clamp 5 mm diameter, 10 pieces
R911173286	Shield clamp 14 mm diameter, 10 pieces
R911173283	Busbar: 10 mm × 3 mm, 1 m long, 1 piece

# 14 Standards and approvals

## 14.1 General information

The products have been developed according to the German editions of the standards published at the time of product engineering.



Loss of conformity due to modifications at the device.

Declarations of conformity, certifications and corresponding markings apply only to the device upon delivery. After modifying the device, verify the conformity and certification.



For the currently valid declarations of conformity and certificates, go to: ➔ „DCTC-30455“

## 14.2 Standards used

Standard	Title
EN 60204-1	Safety of machinery Electrical equipment of machines
EN 61131-2	Programmable logic controllers Part 2: Equipment requirements and tests
EN 60529	Degrees of protection provided by enclosures (IP code)
EN 61010-2-201	Safety requirements for electrical equipment for measurement, control and laboratory use Part 2-201: Particular Requirements for Control Equipment
UL 61010-2-201	UL Standard for Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use Part 2-201: Particular Requirements for Control Equipment

### 14.3 CE conformity



The ctrlX I/O modules comply with the requirements and the target of the EU directives and the harmonized European standards specified in the declaration of conformity.

Table 3: Normen zur elektromagnetischen Verträglichkeit (EMV) – Standards for electromagnetic compatibility (EMC) – Normes sur la compatibilité électromagnétique (CEM)

Norm Standard Norme	Bedeutung Meaning Signification	Ausgabe Edition Édition
DIN EN 61000-6-2	Elektromagnetische Verträglichkeit (EMV) Teil: 6-2: Fachgrundnormen – Störfestigkeit für Industriebereiche Normes génériques – Immunité pour les environnements industriels	November 2019
DIN EN 61000-6-4	Elektromagnetische Verträglichkeit (EMV) Teil: 6-4: Fachgrundnormen – Störaussendung für Industriebereiche Normes génériques – Norme sur l'émission pour les environnements industriels	September 2011



For the CE declaration of conformity, go to the Bosch Rexroth media directory: [www.boschrexroth.com/MediaDirectory](http://www.boschrexroth.com/MediaDirectory), search term ["DCTC-30455-002"](#).

### 14.4 UKCA conformity



The ctrlX I/O modules comply with the UK directive acc. to S.I. 2016/1091 (Electromagnetic Compatibility).



For the UK declaration of conformity, go to the Bosch Rexroth media directory: [www.boschrexroth.com/MediaDirectory](http://www.boschrexroth.com/MediaDirectory), search term ["DCTC-30455-032"](#).

### 14.5 UL/CSA-certified



For the certification under file no. E210730, go to <https://iq.ulprospector.com/en/profile?e=3996827>.

The certification was carried out according to:

- UL 61010-2-201 (Industrial Control Equipment) and
- CSA22.2 No. 61010-2-201 (CSA)

However, there can be modules with a limited or missing certification. Use the data sheet and labeling on the module to check whether approval has been granted. Follow the notes given in this application manual and in the relevant module data sheet.



## 15 Diagnostic and status displays

### 15.1 Diagnostic mechanisms

Different mechanisms are used for the diagnostics of the modules. Note that not all mechanisms are available for every module and that there may be minor module-specific deviations. Check the module-specific data sheet.

Mechanism	Diagnostics
EtherCAT state machine	EtherCAT system diagnostics
EtherCAT hardware watchdog	
Diagnostic objects in the CoE object directory	Extended diagnostics, e.g. peripheral errors
10F1(hex)	Error settings
Diagnosis history object	20 diagnostic messages can be stored
10F3(hex)	Diagnosis history
Module status LED	The module status LED at the top edge of the housing indicates the general module status
Channel status LED	Signals the channel status or the error states
NET status LED	Signals the EtherCAT slave state



Passive modules do not have a module status LED installed, as they are not active devices in the bus system. These include, for example, potential distribution modules, empty housing modules and passive boost modules.

### 15.2 Diagnosis history

The object 10F3(hex) is implemented as ring memory into the "Overwrite mode". The latest 20 diagnostic messages are stored. Older messages are deleted.

The following table shows the structure of the Diagnosis History object.

Index (hex)	Subindex	Object name	Data type	Rights	Meaning
10F3		Diagnosis history			Diagnostic statistics
	01	Maximum messages	UINT8	R	Maximum number of messages
	02	Newest message	UINT8	R	Latest message
	03	Newest acknowledged message	UINT8	R/W	Latest confirmed message. Writing "0" deletes the messages in the ring memory.
	04	New messages available	Boolean	R	New message available
	05	Flags	UINT16	R/W	Setting of the object response. Refer to ETG.1020
	06 - 26	Diagnosis message	String	R	Diagnostic message according to ETG.1020

### 15.3 Status codes in the Diagnosis History

The status codes are module-specific. Please refer to the data sheet of the respective module.

## 15.4 Module status LED (diagnostic and device status)

Device state	LED flashing pattern
Bootng or firmware update	BU BU BU BU BU -- -- -- -- ↻
Initialization or firmware update completed	BU BU BU BU BU BU BU BU BU BU BU ↻
It is currently configured. Module not yet ready.	GN GN GN GN GN -- -- -- -- ↻
Process data transmission, outputs inactive.	GN GN GN GN GN GN GN GN GN GN -- ↻
Module in "Run" state	GN GN GN GN GN GN GN GN GN GN GN ↻
<b>Error and warning states</b>	
Logic or peripheral voltage error	RD RD RD RD RD RD RD RD RD RD RD ↻
Communication or configuration error	RD RD RD RD RD -- -- -- -- -- ↻
Channel error	YE YE YE YE YE -- -- -- -- -- ↻



One square corresponds to a period of 200 ms.

The arrow represents the end of a cycle.

- --: LED is not on.
- BU: LED is blue.
- GN: LED is green.
- RD: LED is red.
- YE: LED is yellow.



A new status is only displayed after the previous flashing cycle has elapsed. A change in status can thus be delayed up to two seconds.

## 15.5 NET status LED

The NET status LED according to the EtherCAT specification (ETG.1300) displays the EtherCAT bus state at the module.

The operating state is displayed in green **GN**:

LED color green	Description
Off	Status INIT
Flickers	Status BOOT
Flashes	Status PRE-OP
Single flash	Status SAFE-OP
Lit	Status OP

The error state is displayed in red **RD**:

LED color red	Description
Off	No error
Flickers	Boot error
Flashes	Invalid configuration
Single flash	Local error (e.g. synchronization)
Double flash	Watchdog error
Lit	Communication error

## 15.6 Channel status LED

The availability and function of the channel status LED are module-specific. Thus, refer to the data sheet of the respective module.

## 16 Commissioning

### 16.1 IT security

Operating systems and machines requires the implementation of a comprehensive concept for state-of-the-art IT security. Bosch Rexroth products are part of this comprehensive concept. The properties of the Bosch Rexroth products have to be considered for a comprehensive IT Security concept. For the required properties, refer to the IT Security Guideline (→ [R911342562](#)).

### 16.2 Device description files ESI

The device description files are provided with the ctrlX I/O Engineering installation.

For new versions of the ESI files or ESI files for the integration, go to → <http://www.boschrexroth.com/electrics>, search term "→ ESI files".

### 16.3 Parameterizing modules

The parameters that can be configured in the CoE objects are usually not saved remanently by the modules. To automatically load the settings required upon each bus start, set the values in the start parameters of the Engineering.

## 17 License information

### 17.1 EtherCAT®



The ctrlX I/O modules use EtherCAT® technology. "EtherCAT®" is a registered trademark and patented technology licensed by the Beckhoff Automation GmbH, Germany. EtherCAT is an open, internationally standardized standard and developed further by the "EtherCAT Technology Group" (ETG).

## 18 Disposal

Dispose the products according to the respective valid national standards.

## 19 Service and support

Our worldwide service network provides an optimized and efficient support. Our experts provide you with advice and assistance. You can contact us **24/7**.

### Service Germany

Our technology-oriented Competence Center in Lohr, Germany, is responsible for all your service-related queries for electric drive and controls.

Contact the **Service Hotline** and **Service Helpdesk** under:

Phone: **+49 9352 40 5060**

Fax: **+49 9352 18 4941**

Email: ➔ [service.svc@boschrexroth.de](mailto:service.svc@boschrexroth.de)

Internet: ➔ <http://www.boschrexroth.com>

Additional information on service, repair (e.g. delivery addresses) and training can be found on our internet sites.

### Service worldwide

Outside Germany, please contact your local service office first. For hotline numbers, refer to the sales office addresses on the internet.

### Preparing information

To be able to help you more quickly and efficiently, please have the following information ready:

- Detailed description of malfunction and circumstances
- Type plate specifications of the affected products, in particular type codes and serial numbers
- Your contact data (phone and fax number as well as your e-mail address)

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